



# Measuring power grid signals in the presence of reduced system inertia

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EURAMET workshop 01.12.2021

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### The context

- Power systems are large, nonlinear, multi-time-scale, discrete/continuous complex systems.
- Usually analyzed for specific problems with relatively simplified models under appropriate assumptions, e.g.
  - Dynamics (electromechanical) dominated by the response of synchronous machines → use of time-varying phasors.
  - Electromagnetic transient models when time-varying phasors are not appropriate.
- The increased penetration of converter-interfaced generation (CIG) and HVDC in power systems challenges the above decomposition of power system studies into phasor-based vs electromagnetic-transient-based.
- New needs in dynamics, control and stability studies of systems with significant penetration of CIG.

### The context

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### Event of September 28, 2016, Australia

Multiple tornadoes in South Australia (SA) tripped multiple 275 kV transmission circuits, and resulted in multiple faults in quick succession.

The series of voltage dips from the faults triggered protection on several wind farms to runback about 456 MW of wind generation.

The reduction in wind farm output was compensated by an increase in power imported from Victoria. However, the import reached a level that tripped the interconnector on loss of synchronism protection.

The loss of power infeed from the wind farms and import from Victoria resulted in the frequency falling so fast that load shedding schemes were unable to stop the fall, resulting in a blackout.



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### Adequacy of signal processing techniques



#### Energy of the signal in [48, 52] Hz 99.X%

#### Narrow-band signals: discrete

spectrum with energy concentrated around a single, or finite and discrete set, of sinusoidal components.

#### Transient with ROCOF *R*=-6.25 Hz/s

```
v(t) = A \cdot cos(2\pi(f - Rt)t)
```



### Energy of the signal in [48, 52] Hz 32%

**Broad-band signal:** continuous spectrum of generic bandwidth where the spectrum of the signal (and its energy) cannot be reconstructed by a finite and discrete set of sinusoidal components.

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### Adequacy of signal processing techniques



- Numerical experiment carried out using the EMTP-RV
- Voltage generator: 380 kV (ph-ph), generic time-dependent voltage source
- Line: 100 km frequency-dependent model
- Load: R-L parallel equivalent  $\rightarrow$  400 MW,  $cos\phi$  0.9
- $v_A(t)$  negative frequency ramp characterized by RoCoF of -5 Hz/s (starting from 50 Hz)
- $v_A(t)$  amplitude modulation characterized by 10% depth and 5 Hz modulating frequency

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### Adequacy of signal processing techniques

Phasor analysis based on IEC Std. 61000-4-7, sliding window of 200 ms.

1:  $p(t) = \sum_{abc} v(t) \cdot i(t)$ True instantaneous power 2: for  $x(t) = \{v(t), i(t)\}_{abc}$  $x(t) = x(t) + \mathcal{N}(t)$ 3: Noise adding, SNR = 80 dB4: for  $t = 0 \rightarrow end$ ,  $\Delta t = 200ms$ ,  $\Delta f = 5Hz$ 5:  $X(k) = \mathcal{F}[x(t) \cdot w(t)]$ Hanning window,  $\mathcal{F} \approx \text{DFT}$  $\{\tilde{f}(t), \tilde{A}(t), \tilde{\varphi}(t)\} = IpDFT[X(k)]$ 6: Estimate of the phasor params  $\tilde{x}_{\tau}(t) = \tilde{A}(t)\cos(2\pi\tilde{f}(t)\Delta t/2 + \tilde{\varphi}(t))$ 7: Reconstruct the time-domain signal 8: end for 9: end for 10:  $\tilde{p}_{\mathcal{F}}(t) = \sum_{abc} \tilde{v}_{\mathcal{F}}(t) \cdot \tilde{\iota}_{\mathcal{F}}(t)$ Instantaneous power of the

11:  $\Delta p_{\mathcal{T}}(t) = \tilde{p}_{\mathcal{T}}(t) - p(t)$ 

Instantaneous power of the reconstructed signals Power error

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### Adequacy of signal processing techniques

Frequency ramp of -5 Hz/s applied to  $v_A(t)$ 





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### Adequacy of signal processing techniques

10% amplitude modulation with modulating frequency of 5 Hzs applied to  $v_A(t)$ 

i<sub>B</sub>(t) B

 $V_B(t)$ 

a

-

Transmission

Line





### **Possible solutions**

To overcome the limitations of traditional phasor analysis, two possible approaches:

#### Dynamic phasor analysis

Dynamic phasors have been introduced as an **extension of the phasor concept**, where **fundamental parameter time-derivatives** are included in the signal model.

Enhanced signal models allow for more accurate reconstruction of time-varying parameters and soften the stationarity constraint. However, it is not possible to dissociate dynamic phasor from DFT-based analysis, and they are likely to face similar model inconsistency issues.

#### Functional basis analysis

information theory provides several **transformations and projection bases other than simple DFT** for the analysis of time-varying or continuous spectrum signals.

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# **Dynamic phasors: pros & cons**

- Outperform stationary phasors in dynamic conditions.
- Prove to be compliant with IEEE Std requirements.
- Still rely on narrow-band approximations of signals and cannot represent in a complete way signals characterized by a continuous spectrum (see comparison with Functional Basis Analysis presented next).

### →NEED FOR ALTERNATIVE TRANSFORMATIONS

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# Analysis of Broad-Band Signals in Reduced-Inertia Power Systems Using the Hilbert Transform (HT)

- As seen at the beginning of the tutorial, the exact modeling of inertia-less power systems may require the use of more sophisticated representations other than phasors
  - **Proposal:** Can we project on a different **functional basis** not based on sinusoids that enables us to reconstruct the whole spectrum and, therefore, capable to **model the power transfer on the whole spectrum**?
- The Hilbert Transform (HT) may be the appropriate tool since its use results into negligible errors in the reconstruction of the spectral power transfer in case of extreme power systems transients



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### **Power Systems Transients Using the HT**

Given a generic time varying real signal x(t), its HT is defined as:

$$\tilde{x}(t) = \mathcal{H}[x(t)] = \frac{1}{\pi} P \int_{-\infty}^{\infty} \frac{x(\tau)}{t - \tau} d\tau$$

being P the Cauchy principal value.

The real signal x(t) and its HT form the so-called **analytic signal**:

$$\hat{x}(t) = x(t) + j \cdot \mathcal{H}[x(t)] = x(t) + j \cdot \tilde{x}(t)$$

About the Cauchy principal value: it is used to assign a value to the integral  $\int_{-\infty}^{\infty} \frac{x(\tau)}{t-\tau} d\tau$  which would be undefined when the denominator is null.

The Cauchy p.v. is defined according to the following rule (being f(x) singular at the finite number *b*):

$$p.v. = \lim_{\epsilon \to 0^+} \left[ \int_a^{b-\epsilon} f(x) dx + \int_{b+\epsilon}^c f(x) dx \right]$$

### **HT applied to Power System Transients**

Amplitude Modulation → inter-area oscillations between large system regions

$$x(t) = A \left( 1 + k_a \cos(2\pi f_a t) \right) \cos(2\pi f_0 t + \varphi_0)$$

#### FT

$$\begin{aligned} \mathcal{F}[x(t)] &= \\ &= \frac{A}{2} \cdot \left[ \delta(f - f_0) e^{j\varphi_0} + \delta(f + f_0) e^{-j\varphi_0} + \frac{k_a}{2} \right] \\ &\cdot \left[ \delta(f - (f_0 + f_a)) e^{j\varphi_0} + \delta(f + (f_0 + f_a)) e^{-j\varphi_0} + \delta(f - (f_0 - f_a)) e^{j\varphi_0} + \delta(f + (f_0 - f_a)) e^{-j\varphi_0} \right] \end{aligned}$$

#### HT

$$\widehat{x}(t) = A \cdot [1 + k_a \cos(2\pi f_a t)] \cdot e^{j(2\pi f_0 t + \varphi_0)}$$

A. Derviškadić, G. Frigo and M. Paolone, "Beyond Phasors: Modeling of Power System Signals Using the Hilbert Transform," in IEEE Transactions on Power Systems.

### **HT applied to Power System Transients**

Frequency Ramp → severe system collapse

$$x(t) = A\cos(2\pi f_0 t + \varphi_0 + R\pi t^2)$$

$$\mathcal{F}[x(t)] = \frac{A}{2\sqrt{R}} e^{j\left[\frac{\pi(f-f_0)^2}{R} - \frac{\pi}{4} + \varphi_0\right]} + \frac{A}{2\sqrt{R}} e^{-j\left[\frac{\pi(f+f_0)^2}{R} - \frac{\pi}{4} + \varphi_0\right]}$$

ΗT

FT

 $\widehat{x}(t) = A e^{j \left(2\pi f_0 t + \varphi_0 + R\pi t^2\right)}$ 

A. Derviškadić, G. Frigo and M. Paolone, "Beyond Phasors: Modeling of Power System Signals Using the Hilbert Transform," in IEEE Transactions on Power Systems.

### **HT applied to Power System Measurements**

The derived analytic signals x̂(t) are a closed-form expression of the real-valued signals x(t). E.g. Frequency Ramp:

 $\begin{aligned} x(t) &= A\cos(2\pi f_0 t + \varphi_0 + 2R\pi t^2) \\ \hat{x}(t) &= A e^{j(2\pi f_0 t + \varphi_0 + R\pi t^2)} \end{aligned}$ 

- The HT may provide an exact match between the real-valued time-domain signal and its analytic representation
- If we project the real-valued signal in x(t) over a basis containing the analytic signal in  $\hat{x}(t)$ , we would obtain a projection coefficient that unequivocally identifies the parameters of the signal in x(t).
- How do we engineer this functional basis in order to extract signal parameters with a high level of fidelity?



Goal:

- Extracting valid signal parameters from measured signals in power grids
- Exploit improved representation of signal dynamics using Hilbert Transform

Inspired by:

- Fourier and Wavelet analysis which rely on bases of complex exponentials and wavelet kernels
- Compressed Sensing which use dictionaries of kernels to reconstruct inputs
- → Create a dictionary based on the Hilbert Transform for instantaneous signal parameter extraction

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### **Dictionary Formulation**

- Assumption that the set of possible signal dynamics in the grid is finite
  - Can be spanned by a dictionary of common dynamics (e.g., AM, FR, AS)
  - Dictionary is user-engineered to capture dynamics of interest
- Each atom in the dictionary represents a specific function for a defined set of parameters



A. Derviškadić, G. Frigo and M. Paolone, "Beyond Phasors: Modeling of Power System Signals Using the Hilbert Transform," in IEEE Transactions on Power Systems.

### **Kernel Models**

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$$d = DFT\left[\left(1 + g_A(t)\right) \cdot e^{j\left(2\pi f_0 t + g_{\varphi}(t)\right)}\right]$$

The frequency of the fundamental component is limited to a finite bandwidth between 48 and 52 Hz, for each fundamental frequency, the following vectors are included in D:

A steady-state (SS) sinusoid

$$d = DFT\left[e^{j(2\pi f_0 t)}\right]$$

- A sinusoid characterized by an Amplitude Modulation (AM)

$$d = DFT [(1 + k_m \cos(2\pi f_m t +)) \cdot e^{j(2\pi f_0 t)}]$$
  
$$k_m = 10\%, f_m = [0,5] \text{ Hz}, \varphi_m = [0,2\pi] \text{ rad}$$

A. Derviškadić, G. Frigo and M. Paolone, "Beyond Phasors: Modeling of Power System Signals Using the Hilbert Transform," in IEEE Transactions on Power Systems.

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# **Functional Basis Analysis**

Parameter Identification



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# **Functional Basis Analysis**

#### Parameter Identification



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### **Functional Basis Analysis**

#### Parameter Identification



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# **Functional Basis Analysis**

#### Parameter Identification



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### **Functional Basis Analysis**

#### Parameter Identification



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### **Performance Evaluation**

- Comparison made between:
  - 1. FBA
  - 2. Static phasor method:
    - 2-point iterative IpDFT method (i-IpDFT) [13]
    - Han window and negative spectrum compensation
  - **3.** Dynamic phasor method:
    - Compressed Sensing Taylor-Fourier Multifrequency (CSTFM) method [7]
    - 1<sup>st</sup> and 2<sup>nd</sup> order derivatives approximated
    - Corrections made to static phasor parameters  $(f_0, A_0, \varphi_0)$

M. Bertocco, G. Frigo, C. Narduzzi, C. Muscas, and P. A. Pegoraro, "Compressive sensing of a Taylor-Fourier multifrequency model for synchrophasor estimation," IEEE Trans. on Instr. and Meas., vol. 64, no. 12, pp. 3274–3283, 2015.

A. Derviskadic, P. Romano, and M. Paolone, "Iterative-interpolated DFT for synchrophasor estimation: A single algorithm for P- and M-class compliant PMUs, "IEEE Trans. on Instr. and Meas., vol. 67, no. 3, pp.547–558, Mar. 2018



### **Performance Evaluation**

- Metrics:
  - Time Domain Error (TDE): residuals of time-domain reconstruction

$$TDE = \frac{\|x_{est}(t_n) - x_{ref}(t_n)\|_2}{\sum_{n=1}^{L} |x_{ref}(t_n)|}$$

• Frequency Error (FE): comparing instantaneous frequency at the center of the window [14]

$$FE = \left| f\left(\frac{T_w}{2}\right) - f_{est}\left(\frac{T_w}{2}\right) \right|$$

- **Parameter Error**: parameter estimation error  $e.g., R \ error = |R - R_{est}|$
- Tests:
  - Synthetic signals created for each signal dynamic case
  - 60 ms sliding window (50 fps)
  - 80 dB Guassian noise
  - Tests based on IEEE C37.118 Standard [14]

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### **Amplitude Modulations**





A. Karpilow, A. Derviskadic, G. Frigo, M. Paolone, "Characterization of Non-Stationary Signals in Electric Grids: a Functional Dictionary Approach" (*in review*). IEEE Transactions on Power Systems, 2021.

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# **Frequency Ramps**

 $f_0 = 50.15 Hz, R = [-5,5]Hz/s$ 



A. Karpilow, A. Derviskadic, G. Frigo, M. Paolone, "Characterization of Non-Stationary Signals in Electric Grids: a Functional Dictionary Approach" (*in review*). IEEE Transactions on Power Systems, 2021.

### **Phase Modulations**

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A. Karpilow, A. Derviskadic, G. Frigo, M. Paolone, "Characterization of Non-Stationary Signals in Electric Grids: a Functional Dictionary Approach" (in review). IEEE Transactions on Power Systems, 2021.



# **Amplitude Steps**

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### Parameter Error

Dynamic	Max FE (mHz)			Max RFE (mHz/s)			Mean TDE		
	60 ms	200 ms	IEEE Limit	60 ms	200 ms	IEEE Limit	60 ms		200 ms
SS	0.1	1.6E-2	5	2	1.2	10	8.2E-06		4.5E-06
AM	0.9	0.1	60	32	6	2300	9.9E-6		5.7E-06
FR	5	4.7	10	147	222	400	1E-05		1.8E-05
PM	8	13	60	112	420	2300	1.3E-05		2.4E-05
AS	4	1.3		27	108		1.1e-03		5.2E-04
AM/FR	2	3		223	196		1.4E-05		3.7E-05
AM/PM	8	18	60	276	498	3000	1.9	E-5	3.7E-05
Dynamic	Mean Parameter Error for 200 ms window								
	<i>f</i> <sub>0</sub> (mHz)	$f_m$ (mHz	z) $\varphi_m$ (ra	ad) $f_a$ (n	nHz) $\varphi$	$R_a$ (rad) R	(mHz/s)	k <sub>s</sub> (%)	$t_s$ (ms)
SS	0.2								
AM	0.2	3.5	0.01	8					
FR	5						48		
PM	14			58	8	0.16			
AS	1							2.6	1.5
AM/FR	4	45	0.07	8			30		
AM/PM	13	39	0.04	1 7	6	0.14			

### Conclusions

- Recent events in low-inertia power systems have shown how the use of phasors may lead to large approximations when modelling signals of electrical quantities of reduced-inertia power grids.
- Dynamic phasors outperform stationary phasors in dynamic conditions but still rely on narrow-band approximations of signals and cannot represent in a complete way signals characterized by a continuous spectrum.
- The HT, integrated with the analytical signal representation, may be the appropriate tool for modelling broad-band signals associated to inertia-less power system dynamics.
- The presentation has shown how the functional basis analysis (FBA) allows for the extraction of signal parameters and the identification of common dynamics.
- The FBA method demonstrated improved performance for common signal dynamics and real-world signals when compared to dynamic and static phasor methods.



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