

EUROMET PROJECT

Final Report

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3. Type of collaboration: Consultation on facilities																																																																									
4A. Partners: JV, SP	4B. CEC funded? No																																																																								
5. Participating Countries: NO, SE																																																																									
6. Title: Uncertainty components on line scale measurements																																																																									
7. Final report: This uncertainty budget refers to measurements carried out at JVs laboratories. $\Delta Y = (p_1 - p_0) + \delta L_{\text{sym}} + \delta L_{\text{HP}} + \Delta \phi D + \delta L_{\text{xy}} + \delta L_{\text{focus}} - \Delta T \alpha L$ ΔY Deviation from 1 m. 1. $(p_1 - p_0)$ Reading, distance between position p_1 and p_0. 2. δL_{sym} Correction for different symmetry of the lines, an imaging problem. 3. δL_{HP} Correction for calibration of HP-interferometer. 4. $\Delta \phi D$ Correction for Abbe deviation. 5. δL_{xy} Correction for deviation in alignment of line of movement for reflector. 6. δL_{focus} Correction for deviation in focus. 7. $\Delta T \alpha L$ Correction for deviation in temperature measurement. <table border="1" style="width: 100%; border-collapse: collapse; margin-top: 10px;"> <thead> <tr> <th>X_i</th> <th>x_i</th> <th>u_{xi}</th> <th>Distribution</th> <th>c_i</th> <th>u_{yi}</th> </tr> </thead> <tbody> <tr> <td>$p_1 - p_0$</td> <td>-2.11 μm</td> <td>0.11 μm</td> <td>Normal</td> <td>1</td> <td>0.11 μm</td> </tr> <tr> <td>δL_{sym}</td> <td>0</td> <td>0.20 μm</td> <td>Rect</td> <td>1</td> <td>0.20 μm</td> </tr> <tr> <td>δL_{HP}</td> <td>0</td> <td>0.20 μm</td> <td>Normal</td> <td>1</td> <td>0.20 μm</td> </tr> <tr> <td>$\Delta \phi$</td> <td>0.056 mm/m</td> <td>0.002 mm/m</td> <td>Rect</td> <td>$D = 30 \text{ mm}$</td> <td>0.07 μm</td> </tr> <tr> <td>δL_{xy}</td> <td>0</td> <td>0.10 μm</td> <td>Rect</td> <td>1</td> <td>0.10 μm</td> </tr> <tr> <td>δL_{focus}</td> <td>0</td> <td>0.36 μm</td> <td>Normal</td> <td>1</td> <td>0.36 μm</td> </tr> <tr> <td>ΔT</td> <td>0</td> <td>0.03 K</td> <td>Rect</td> <td>$\alpha L = 8.69 \mu\text{m/Km}$</td> <td>0.26 μm</td> </tr> <tr> <td>α</td> <td>$8.69 \cdot 10^{-6} \text{ K}^{-1}$</td> <td>$1 \cdot 10^{-6} \text{ K}^{-1}$</td> <td>Rect</td> <td>$u(\Delta T) L = 0.05 \text{ Km}$</td> <td>0.05 μm</td> </tr> <tr> <td>ΔY</td> <td>-0.43 μm</td> <td>0.55 μm</td> <td></td> <td>u_y</td> <td>0.55 μm</td> </tr> <tr> <td></td> <td></td> <td></td> <td></td> <td>k</td> <td>2.08</td> </tr> <tr> <td></td> <td></td> <td></td> <td></td> <td>U</td> <td>1.15 μm</td> </tr> </tbody> </table> 10 measurements in each series, 7 measurement series, gives a pool for calculation of uncertainty contribution from repeatability with 63 degrees of freedom. (Comp. 1) Effective degrees of freedom = 33. $k = 2.08$ Result for measurement of M3: $\Delta Y = -0.43 \mu\text{m} \pm 1.15 \mu\text{m}$		X_i	x_i	u_{xi}	Distribution	c_i	u_{yi}	$p_1 - p_0$	-2.11 μm	0.11 μm	Normal	1	0.11 μm	δL_{sym}	0	0.20 μm	Rect	1	0.20 μm	δL_{HP}	0	0.20 μm	Normal	1	0.20 μm	$\Delta \phi$	0.056 mm/m	0.002 mm/m	Rect	$D = 30 \text{ mm}$	0.07 μm	δL_{xy}	0	0.10 μm	Rect	1	0.10 μm	δL_{focus}	0	0.36 μm	Normal	1	0.36 μm	ΔT	0	0.03 K	Rect	$\alpha L = 8.69 \mu\text{m/Km}$	0.26 μm	α	$8.69 \cdot 10^{-6} \text{ K}^{-1}$	$1 \cdot 10^{-6} \text{ K}^{-1}$	Rect	$u(\Delta T) L = 0.05 \text{ Km}$	0.05 μm	ΔY	-0.43 μm	0.55 μm		u_y	0.55 μm					k	2.08					U	1.15 μm
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8. Completion Date: 16.10.00	10. Coordinator's signature: Helge Karlsson	11. Date: 16.10.00																																																																							

Notes for the completion of the form overleaf